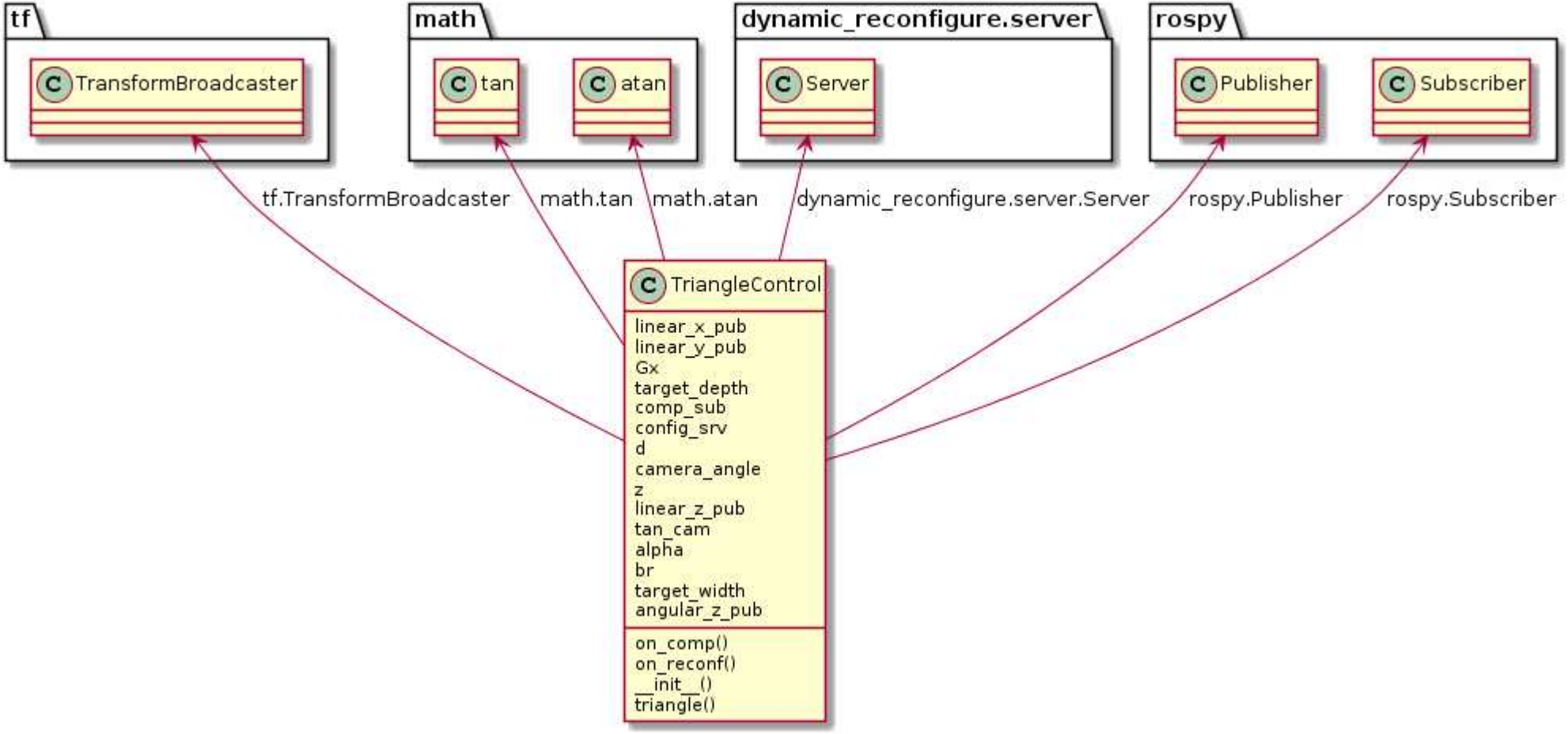
tf
TransformBroadcaster
math
tan
atan
dynamic_reconfigure.server
Server
rospy
Publisher
Subscriber
tf.TransformBroadcaster
math.tan
math.atan
dynamic_reconfigure.server.Server
rospy.Publisher
rospy.Subscriber
TriangleControl
linear_x_pub
linear_y_pub
Gx
target_depth
comp_sub
config_srv
d
camera_angle
z
linear_z_pub
tan_cam
alpha
br
target_width
angular_z_pub
on_comp()
on_reconf()
__init__()
triangle()