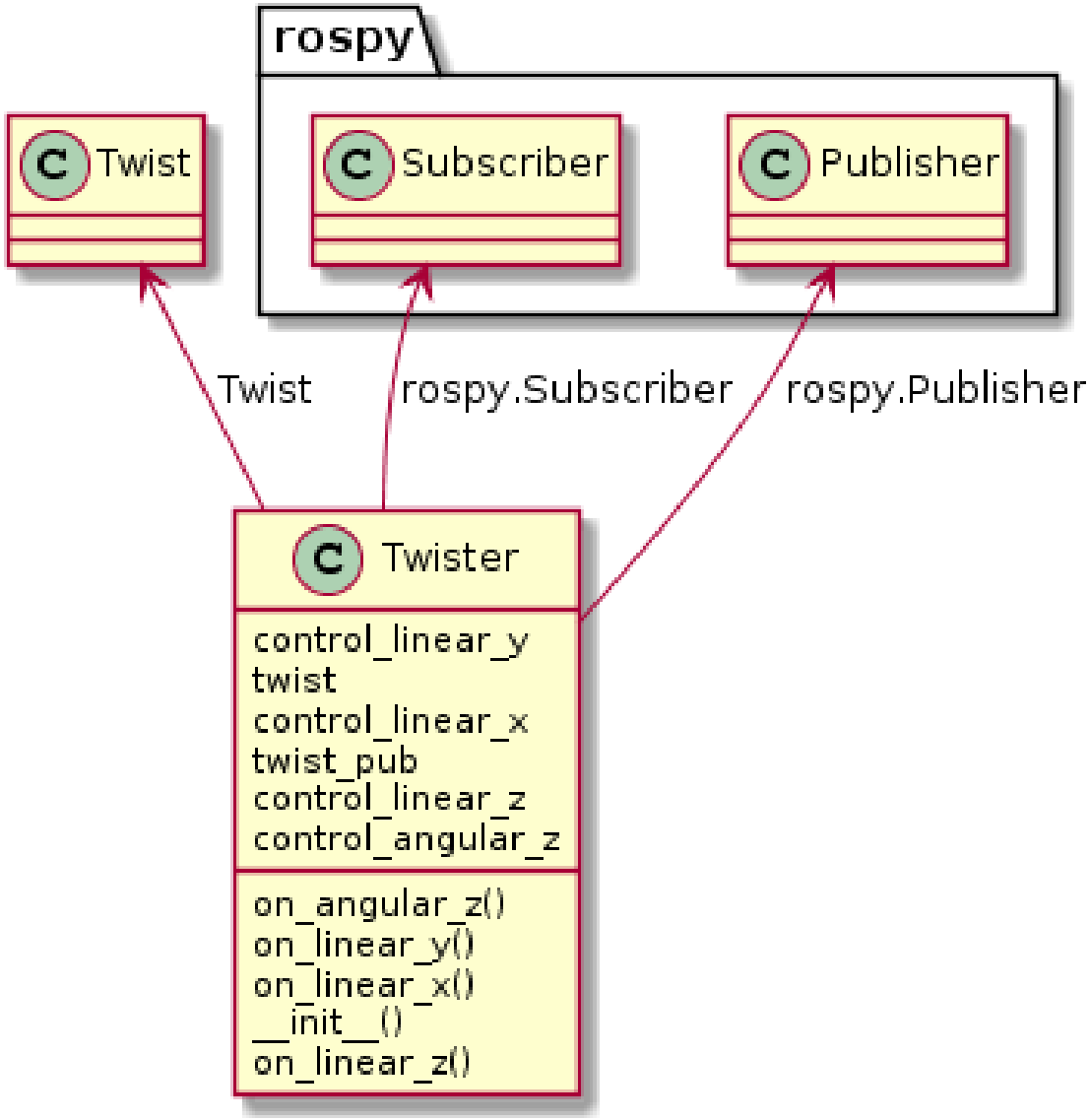
rospy
Twist
Subscriber
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control_linear_y
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control_linear_z
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on_angular_z()
on_linear_y()
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